ANALYSES OF TURBIDITY AND ACOUSTIC BACKSCATTER SIGNAL WITH ARTIFICIAL NEURAL NETWORK FOR ESTIMATION OF SUSPENDED SEDIMENT CONCENTRATION

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Abstract. The commonly used sampling method is restrictive for the spatial and temporal measurement of suspended sediment and requires intensive labor. These limitations and technological advances have led to methods based on sound or light scattering in water. In this study, the turbidity and acoustic backscattering signal (ABS) values were used with the aim of improving these methods with different artificial neural network (ANN) models; Multilayer Perceptron (MLP), Radial Basis Neural networks (RBNN) and General Regression Neural Network (GRNN). Measurements were taken in a vertical sediment tower for two different sediment sizes (< 50 µm and 50-100 µm) and concentrations (0.0- 6.0 g L^{-1}). In the results of the regression analyses, turbidity values had strong relationships with sediment concentration for both sediment size groups ($R^2 = 0.937$ and 0.967). Although the ABS values had a reasonable R² value (0.873) for the 50–100 μ m group, the < 50 μ m group did not produce a significant R² value with regression analyses. The remarkable differences were not observed among MLP, RBNN and GRNN model for this sediment size group, and the reasonable R² and RMSE results were not produced with any ANN model that had a single ABS input for the $< 50 \mu m$ sediment group. On the other hand, for the other sediment group (50–100 μ m), ABS values were used as a single input, and the highest R² (0.917) value was obtained with MLP model and it was improved with the turbidity input (up to $R^2 = 0.999$). The results show that the ANN model could be considered as an alternative method because it was applied successfully to estimate suspended sediment concentration using with turbidity and ABS under different particle size conditions.

Keywords: environmental, water quality, sediment transport, acoustic algorithm, particle size

Introduction

Sediment transport in river is the crucial technical problem for many environmental and engineering practices. But its monitoring has many difficulties especially during high discharge and rough water-level conditions. The direct water sampling method is generally used as traditionally. But it is restrictive to represent spatial and temporal analysis of suspended sediment concentration, (Thorne and Hanes, 2002; Guerrero et al., 2016). Because sediment concentration high variable parameter depends on flow, climate and basin conditions (Gray et al., 2002). The size and concentration of sediment are mainly affected by intensity and volume of precipitation, texture and erodibility of soil, topography and land cover properties (Melesse et al., 2011). In addition; time and labor consumed for sampling and filtering processes are the other limitations of this method (Wren et al., 2000; Schoellhamer and Wright, 2003; Tfwala and Wang, 2016). Besides these limitations, continuous and precision sediment-monitoring requirements have led to new devices, especially in terms of using light and sound scattering or attenuation by particles in water. This new technique has gained importance within the sedimentological community, and its validation has been tested in many laboratory and field studies (Pedocchi and Garcia, 2012).

Turbidity as a physical value is defined as an optical property that causes light to be scattered and absorbed rather than transmitted in straight lines through the sample (APHA, 2012). Scattering and absorption of light occurs on mineral suspended particles, colloids and bacterioplankton units, air bubbles and other suspended materials in the water sample (Lewis and Eads, 2001). The possibility of simultaneous observations of turbidity and its relationship between suspended sediment concentrations (SSC) has led to the use of turbidimetry to monitor sediment transportation (Uncles and Stephens, 2010). The use of turbidity values for SSC is an indirect method and based on determination of the statistical relationship between these values; the relationship could be linear, non-linear or polynomial (Sun et al., 2001). In addition the Regression equation should be considered individually for each stream condition with variations following the change of hydrological seasons (Williamson and Crawford, 2011). Changes in sediment size, mineral composition and water quality properties are the main limitations of this method. These effects should be considered and defined for different conditions to more accurately estimate sediment concentration with turbidity values (Ziegler, 2002). Tananaev and Debolskiy (2014) reported that the effecting factors of turbidity and sediment grain size should be considered in multivariate models, to minimize errors and acquire an understanding of its response. Mitchell et al. (2003) conducted a turbidity study using river conditions, and they reported that water quality and sediment properties were strongly affected, leading to errors in turbidity measurements, especially in spring season conditions. Chanson et al. (2008) conducted a laboratory study and produced a strong relationship ($R^2 = 0.992$) between sediment concentration and turbidity (Nephelometric Turbidity Units, NTU) at low concentrations (0.8 g L^{-1}) for silt and sand sediment materials. Slaets et al. (2014) used the cumulative rainfall values as additional input parameter to estimate sediment concentration with turbidity measurement. Pearson's correlation coefficient was improved with Multiple linear regression analyses up to 0.87 compared with single (turbidity) parameter.

The acoustic sediment measurements, as other new technology, are based on sound waves spreading through the water column. The strength of the sediment particles' backscattered signal is used to estimate the particles' properties. The sediment particle size and concentration in the water can be computed using multi-frequency acoustic backscattering signal (ABS). For this purpose, three or four frequencies in the range 0.5–5 MHz are usually used in transceiver and receiver mode (Thorne and Meral, 2008). Acoustic sediment measurement studies have been applied successfully under different field and laboratory conditions. These studies' results confirmed that particle size and concentration using ABS (Thorne and Hurther, 2014; Ruessink et al., 2011; O'Hara Murray et al., 2012; Aagaard, 2014; Thosteson and Hanes, 1998; Thorne et al., 1998). However ABS is an indirect method and an inversion algorithm is required to convert the backscattered signal to a sediment concentration (Wilson and Hay, 2015; Clay and Medwin, 1997).

The main principle of ABS can be defined using the backscattering and attenuating characteristics of the particles in suspension, which are used for the acoustic inversion algorithm. The backscattering characteristic of the sediment particles is represented with

the form function, and the attenuation characteristic is represented with the normalized total scattering cross-section. Both are non-dimensional parameters, and their origins are based on the acoustic properties of sphere particles (Neubauer et al., 1974). The sphere scattering properties, using the form function and normalized total scattering cross-section, were first reported by Sheng and Hay (1988). They used a solid sphere model and formulated a simple expression agreed with the data. Many researchers have adopted a similar expression (Thorne and Hurther, 2014; Hay and Sheng, 1992; Crawford and Hay, 1993; Thorne and Hardcastle, 1993; Schaafsma and Hay, 1997; Kisi, 2005). Thorne and Meral (2008) produced an expression for backscattering and attenuating characteristics that compared well with all the data sets available and that could be used with a reasonable degree of confidence to interpret ABS data collected above sandy sediments.

Many researchers have applied the backscattering signal to estimate suspended sediment, but difficulties and complexity remain in the acoustic algorithm. This requirement has led to alternative approaches to formulating the inversion (Thorne and Hurther, 2014). An artificial neural network (ANN) can be used to estimate a suspended sediment concentration based on the measured backscattered signal strength. The ANN technology has provided reasonable results in many complex nonlinear models used in hydrological studies. Kisi (2005) investigated the performance of the neural network method for modeling suspended sediment transportation. Nourani and Kalantari (2010) used rainfall and runoff parameters to determine spatiotemporal modeling of sediment with Artificial Neural Network. Maanen et al. (2010) used an ANN model to predict the suspended sediment with the input variables flow velocity, water depth and wave height, and they reported that using ANN models can improve sediment transport monitoring. Wang et al. (2009) used flow rate and turbidity values as input parameters for an ANN model to estimate sediment concentration, obtaining reasonable results. Similar ANN models studies have been used for many different types of input data, and strong correlations have been obtained for sediment prediction (Abrahart and White, 2001; Nagy et al., 2002; Yitian and Gu, 2003; Cigizoglu, 2004; Alp and Cigizoglu, 2007).

In this study, an acoustic backscattering signal (ABS) and the turbidity method were used for two different sediment-size groups in laboratory conditions. The study aimed to improve both methods by using regression and different ANN models to reduce the complexity of the acoustic algorithm.

Materials and methods

This study was conducted in a 50-L sediment tower under laboratory conditions. The sediment tower was used to prepare homogenous suspended sediment, which was mixed with a propeller operated by an electric motor. Natural sediment materials were used for both the 0–50 μ m and 50–100 μ m groups. Nearly 60 different concentrations were prepared, up to 6.0 g L⁻¹ for both sediment-size groups.

An AQUAscat-L (Aquatec Group) device was used with 2 MHz frequency for the acoustic backscattering measurements (*Fig. 1*). The transducer was fixed vertically at the top of the tower, and backscattered signals were measured at 0.01 m intervals for each second during a 2-min period for both sediment groups. Turbidity measurements were made simultaneously with ABS using a Seapoint Turbidity Meter (*Fig. 1*). This device detects light scattered by suspended particles in water and produces an output

voltage. The output voltage is calibrated to turbidity in formazine turbidity units (FTU). The unique optical design confines the sensing volume to within 5 cm of the sensor, allowing near-bottom measurements and minimizing errant reflections in restricted spaces (Smerdon, 2006). The measured data were saved by an external data logger. The turbidity sensor read 60 values per minute and a total of 120 turbidity values were taken during a 2-min period for each concentration. In addition, tree water samples (250 mL) were taken to determine the real sediment concentration with the gravimetric method.



Figure 1. The AQUAscat-L (Aquatec Group) device and Seapoint Turbidity Meter sensor

The regression analyses were applied to obtain the relationship between the sediment concentration with the ABS signal and the turbidity values. These relationships were evaluated using determination coefficient (\mathbb{R}^2), root mean squared error ($\mathbb{R}MSE$) and mean absolute error ($\mathbb{M}AE$). As an alternative method, the ANN method was carried out to estimate sediment concentration using the ABS and turbidity values. In addition, a single input parameter was performed to get a simple alternative for sediment measurement. Different network topologies with single or double hidden layers and varying numbers of neurons were created using the Neural Network Toolbox for MATLAB software. Structures of ANN models are given in *Figure 2*. The measured data set was used 70% for training and 30% for testing, producing an ANN model. Finally, the ANN models were evaluated using \mathbb{R}^2 , $\mathbb{R}MSE$ and $\mathbb{M}AE$.

Although there are many alternative models of ANN, in this study the Multilayer Perceptron (MLP), Radial Basis Neural networks (RBNN) and General Regression Neural Network (GRNN) were applied. A feed forward MLP network is formed by simple neurons called perceptron. The perceptron computes a single output from multiple inputs by making a linear combination according to its input weights and then determining the output through a nonlinear transfer function (Singha et al., 2012). The RBNN network is feed-forward network trained using a supervised training algorithm. The RBNN has connection weights between the hidden layer and the output layer only and an activation function is used as radial basis. It does not perform parameter learning as in MLP, performs linear adjustment of the weights fort the radial bases. The RBNN usually train much faster than back propagation networks. They are less susceptible to problems with non-stationary inputs because of the behavior of the radial basis function hidden units. The GRNN is a variation of the RBNN and is based on kernel regression networks. It consists of four layers: input layer, pattern layer, summation layer and output layer. The GRNN is based on the non-linear regression model. It estimates most probable output values for given input training set with the minimum mean-squared error (Cigizoglu, 2004; Alp and Cigizoglu, 2007).



Figure 2. Structures of ANN models for sediment concentration estimation. a) Single input layer (ABS). b) Single input layer (Turbidity). c) Double input layer (ABS and Turbidity)

Results and discussion

The results show that small particles had the greatest turbidity and decreasing in turbidity values depended on increases in sediment size (*Fig. 3*).



Figure 3. Observed turbidity (a) and ABS values (b) for different sediment concentrations

Similarly, Gao et al. (2008) reported that turbidity is more sensitive to fine particles than to coarse particles. This property has led to investigate the relationship between particle size distribution and turbidity. Yao et al. (2014) used different particle size and investigate its relationship with turbidity. They obtained strong correlation for bigger than 5 micron sediment size but reasonable relation was obtained only for low turbidity (0–40 NTU) under smaller sediment condition. Pavanelli and Bigi (2005) reported that a large deviation in sediment size can lead to serious errors in estimating. They prepared sediment sample groups with narrow intervals (19–31, 58–81 and 124–149 μ m), and

they obtained good relationships. They concluded that sediment size problems can be eliminated with sensitive calibration but it should be consider the flow regime and water color for each river condition.

ABS measurements were observed in a large and unstable range for fine-sediment materials. Previous studies stated that clay's existence in the sediment suspension negatively effects of ABS values. This problem is essentially explained with the shape of a fine sediment (Moate and Thorne, 2009), for particle coagulation depends on the clay material, which causes unstable backscattering (Thorne and Hanes, 2002). In addition, this study's results showed that the negative effect of clay depends on the sediment concentration, especially above the level of 4.0 g L⁻¹. This situation limits the uses of the acoustic method in certain clay-content conditions.

Regression analyses

The average FTU and ABS values for each known sediment concentration were used for regression analyses. The statistical parameters (RMSE, MAE and R^2) values of the linear regression analysis results between sediment concentration and FTU and between sediment concentration and ABS are presented *Table 1* for training and testing data. In addition estimated and measured SSC values were plotted in *Figure 4* to show comparison of models for testing data.

Inputs		Training		Testing			
	RMSE	MAE	\mathbf{R}^2	RMSE	MAE	\mathbf{R}^2	
	For smaller than 50 µm sediment group						
ABS	1.338	1.107	0.311	1.480	1.253	0.274	
FTU	0.467	0.365	0.934	0.428	0.370	0.937	
FTU and ABS	0.430	0.326	0.947	0.491	0.417	0.918	
	For the 50–100 µm sediment group						
ABS	1.094	0.938	0.904	1.210	1.050	0.873	
FTU	0.185	0.139	0.988	0.340	0.210	0.967	
FTU and ABS	0.175	0.130	0.990	0.360	0.200	0.961	

Table 1. The statistical parameters (RMSE, MAE and R^2) values of the linear regression analysis results



Figure 4. Regression analyses between sediment concentration (SSC) with turbidity (FTU) and acoustic backscattering signal (ABS), (a) $< 50 \ \mu m$, (b) 50–100 μm sediment group

The turbidity values had good relationships with the SSC values ($R^2 = 0.937$ and 0.967) for testing data of each sediment groups respectively. However, the linear relationship was destroyed for values higher than 700 FTU, and this critical level was reached at the 3 g L⁻¹ sediment concentration for the small particle size. The Seapoint Turbidity manual reported that the sensor response becomes nonlinear above 750 FTU; however, the useful range can be extended by calibrating the sensor and fitting the response to a second-order polynomial equation. Similarly, Wang et al. (2014) reported that values up to 600 FTU had good relations with SSC. It can be concluded that turbidity measurements should be conducted for lower sediment concentrations and that subsamples with dilution should be used for high concentrations (Foster et al., 1992). Due to negatively effect of small particle size, relatively lower R^2 values were obtained for ABS measurements compared to turbidity values. Although ABS had a reasonable R^2 value (0.873) for the 50–100 µm sediment group, but a significant R^2 (0.274) was not produced for $< 50 \,\mu m$ sediment group. In addition, all regression equations can be used for the low-sediment concentration condition. Increasing sediment size can provide these equations for up to a 4 g L^{-1} concentration. Medalie et al. (2014) obtained a moderately strong relation ($R^2 = 0.650-0.810$) was found for concentrations of finegrained suspended sediments and backscatter signals up to 500 mg L⁻¹ sediment concentration. However, a quite weak relationship ($R^2 = 0.220-0.370$) was observed for fine sediment for some river conditions in the same study. This problem is not related to the regression method; rather, it is a result of the problems observed in the acoustic measurement.

ANN models

The statistical parameters (RMSE, MAE and R^2) of each ANN models were used to evaluate the alternative approaches (*Tables 2 and 3*). The reasonable \mathbb{R}^2 and RMSE results were not produced with the any ANN model that had a single ABS input for the < 50 µm sediment group, and it was not considered for discussion in Table 3. This problem is caused by the negative clay particles on the ABS sediment, as mentioned above, and it was not improved with ANN models. These results show that ABS is strongly affected by sediment grain size, thus supporting the findings of previous studies. Similarly, De Falco et al. (2010) reported that backscatter signal strongly affected by sediment grain size; being directly correlated to the weight percent of the coarse fraction (1000–1600 μ m) and inversely correlated to weight percent of the finer sediments (16-500 µm). Goff et al. (2004) did not find a significant relationship between backscatter intensity and the mean grain size of sands (>4000 μ m), although they found an inverse relationship with finer sediments (0.063 µm). This can be explained deviation of size and distribution. Therefore, in this study; strong relationships were obtained using a single turbidity input, with the highest R^2 (0.970) for the MLP, and R^2 (0.999) values in RBNN and GRNN model for testing. The use of ABS values as additional inputs (along with turbidity) did not improve the statistical parameters of this relationship. The remarkable differences were not observed among MLP, RBNN and GRNN model for this sediment size group. On the other hand, for the other sediment group (50-100 µm), ABS values were used as a single input, and the highest R² (0.917) and lowest RMSE (0.521) values were obtained for the MLP among all ANN models (Table 2). De and Chakraborty (2012) concluded that estimating the mean grain size using an acoustic inversion algorithm is computing-intensive, but this value could be estimated using an ANN-based approach in a much shorter computing

time and with high determination coefficients (R^2 up to 0.998). Similarly this study shows that single ABS input values can be used with any ANN model to estimate SSC instead of the complex acoustic algorithm. The using single turbidity for input for the 50–100 µm sediment group produces good relationships with the highest R2 (0.986) for the MLP, and R^2 (0.996) values in RBNN and GRNN model for testing. In addition, for the relatively coarse sediment group, the using ABS values as an additional input with turbidity showed an improved relationship with R^2 : 0.973 0.999 and 0.999 for MLP, RBNN and GRNN models respectively.

Inputs	Model	Training			Testing		
		RMSE	MAE	R ²	RMSE	MAE	R ²
FTU	MLP	0.209	0.151	0.983	0.397	0.296	0.970
FTU and ABS	MLP	0.272	0.167	0.971	0.417	0.329	0.940
FTU	RBNN	0.183	0.106	0.988	0.280	0.120	0.990
FTU and ABS	RBNN	0.187	0.093	0.987	0.290	0.160	0.990
FTU	GRNN	0.116	0.042	0.995	0.250	0.100	0.990
FTU and ABS	GRNN	0.160	0.080	0.990	0.260	0.130	0.990

Table 2. The statistical evaluation of different ANN models for the $< 50 \mu m$ sediment group

Table 3. The statistical evaluation	tion of different ANN	models for the 50–100	µm sediment
group			

Inputs	Model	Training			Testing		
		RMSE	MAE	R ²	RMSE	MAE	R ²
ABS	MLP	0.286	0.222	0.972	0.400	0.187	0.936
FTU	MLP	0.131	0.102	0.994	0.278	0.202	0.986
FTU and ABS	MLP	0.142	0.094	0.993	0.297	0.170	0.973
FTU	RBNN	0.068	0.032	0.998	0.110	0.050	0.996
FTU and ABS	RBNN	0.079	0.035	0.998	0.050	0.030	0.999
FTU	GRNN	0.051	0.035	0.999	0.060	0.040	0.999
FTU and ABS	GRNN	0.032	0.023	0.999	0.370	0.280	0.953

Conclusions

Many researchers have used the acoustic method for estimating sediment concentration in both laboratory and river conditions. Sound-scattering properties are known to become more complex with different particle sizes and sediment concentrations (Thorne and Hanes, 2002; Mouraenko, 2004). Although the acoustic algorithm is the basic method for evaluating ABS, many parameters – such as sediment and water properties, flow regime and acoustic device settings – are required to estimate sediment concentration, This method is quite complex, requires user expertise, and has some disadvantages (Meral et al., 2008). Comparatively, the ANN model is not complicated, and it can be a reasonable alternative for evaluating ABS values, In addition, turbidity values have a strong relationship with a wide range of sediment concentrations at different particles sizes, and these turbidity values can be used as a single input parameter to estimate sediment concentration as an alternative to the

acoustic method. This study's results show that the acoustic method has potential for instantaneous and continuous sediment concentration analysis with reasonable precision, and it can be improved upon using regression and ANN models, The ANN model is a powerful tool for input/output mapping, and it can facilitate the acoustic method by removing complex algorithms. A single input parameter (turbidity or ABS) can be used with the ANN model for all waters not containing clay, to get more accurate results, further regression and ANN model studies should be conducted with alternative particle sizes, shapes and densities and for varying water properties.

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